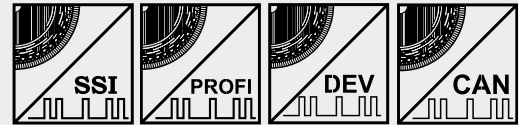


POSIWIRE®
WS19KT
Absolute Encoder Output



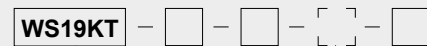
Robust Sensor with heavy duty encoder

- Protection class IP64
- Measurement range 0 ... 2000 mm to 0 ... 15000 mm
- Absolute encoder output



Specifications	Outputs	See order code	
	Resolution for 12 bit per revolution (4096 steps/revolution)	WS19KT-2000 WS19KT-3000 WS19KT-5000 WS19KT-8000 WS19KT-15000	Resolution 0.04 mm 0.063 mm 0.10 mm 0.162 mm 0.146 mm
Linearity	±0.05% f.s.; ±0.01% f.s. as option		
Sensing device	Absolute encoder		
Material	Aluminum and stainless steel; cable: stainless steel		
Protection class	IP64		
Connection	Depend on the encoder type: connector or bus cover		
Weight	See table page 28		
EMC, temperature	Refer to output specification		

Order code WS19KT



Model name

Measurement range (in mm)

2000 / 3000 / 5000 / 8000 / 15000

Outputs

- HSSI = Absolute encoder with synchronous serial output (SSI)
- HPROF = Absolute encoder with Profibus interface
- HINT = Absolute encoder with Interbus interface
- HDEV = Absolute encoder with DeviceNet interface
- HCAN = Absolute encoder with CAN interface
- HCANOP = Absolute encoder with CANopen interface

Linearity (option)

L01 = ±0.01% f.s.

Cable fixing

- M4 = M4 cable fixing
- SB0 = Cable clip

Order code mating connector

HSSI: **CONN-CONIN-12F-G**

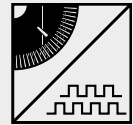
Order example: WS19KT - 3000 - HSSI - M4

POSIWIRE® WS19KT Incremental Encoder Output



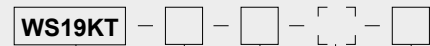
Robust Sensor with heavy duty encoder

- Protection class IP64
- Measurement range 0 ... 2000 mm to 0 ... 15000 mm
- Incremental encoder output



Specifications	Outputs	Incremental output TTL or HTL compatible	
	Resolution for 12 bit per revolution (4096 steps/revolution)		WS19KT-2000
		WS19KT-3000	15.75 pulses
		WS19KT-5000	10 pulses
		WS19KT-8000	6.13 pulses
		WS19KT-15000	6.83 pulses
Linearity	±0.05% f.s.; ±0.01% f.s. as option		
Sensing device	Incremental encoder		
Material	Aluminum and stainless steel; cable: stainless steel		
Protection class	IP64		
Connection	Male 12 pin socket		
Weight	See table page 28		
EMC, temperature	Refer to output specification		

Order code WS19KT



Model name

Measurement range (in mm)

2000 (smaller measurement ranges included) / 3000 / 5000 / 8000 / 15000

Outputs

LD5VC = Incremental encoder TTL compatible

PP24VC = Incremental encoder HTL compatible

Linearity (option)

L01 = ±0.01% f.s.

Cable fixing

M4 = M4 cable fixing

SB0 = Cable clip

Order code mating connector

CONN-CONIN-12F-G

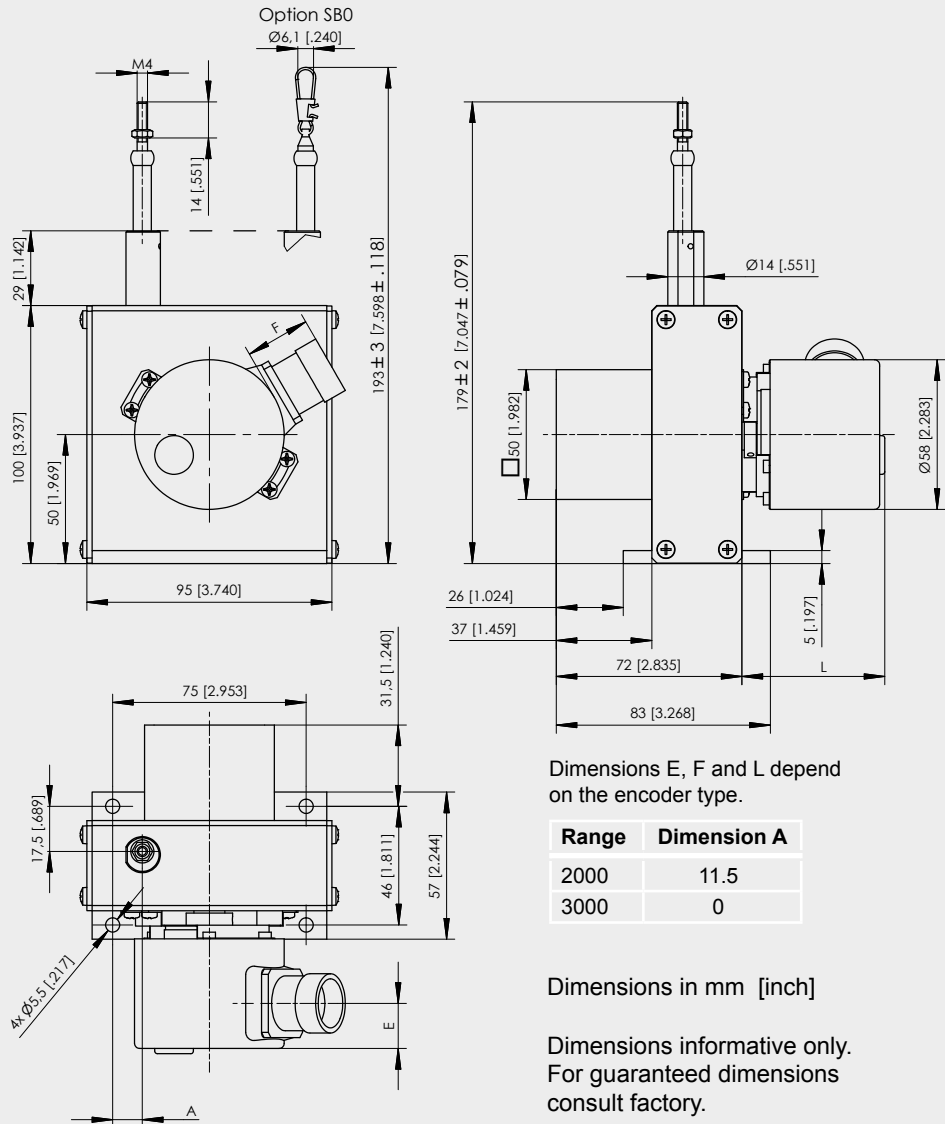
Order example: **WS19KT - 5000 - LD5VC - M4**

POSIWIRE® WS19KT Absolute or Incremental Encoder Output



Cable forces, typical at 20 °C	Range	Weight (approx.)	Max. pull-out force	Min. pull-in force
	[mm]	[kg]	[N]	[N]
	2000	1.3	11.0	6.0
	3000	1.6	8.1	4.9
	5000	3.0	12.0	9.0
	8000	5.6	10.5	6.8
	15000	6.1	16.5	9.1

Outline drawing WS19KT-2000 / 3000

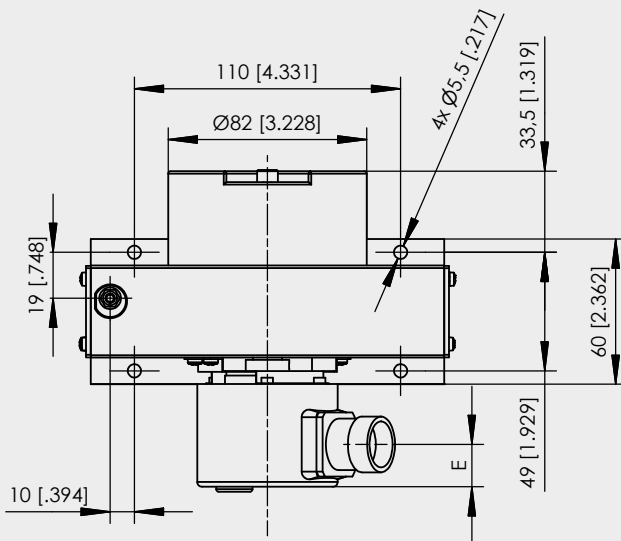
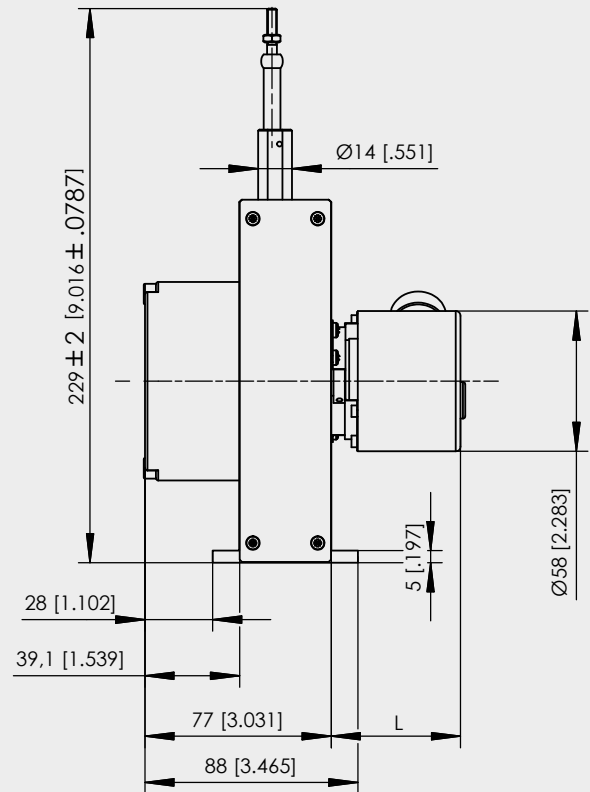
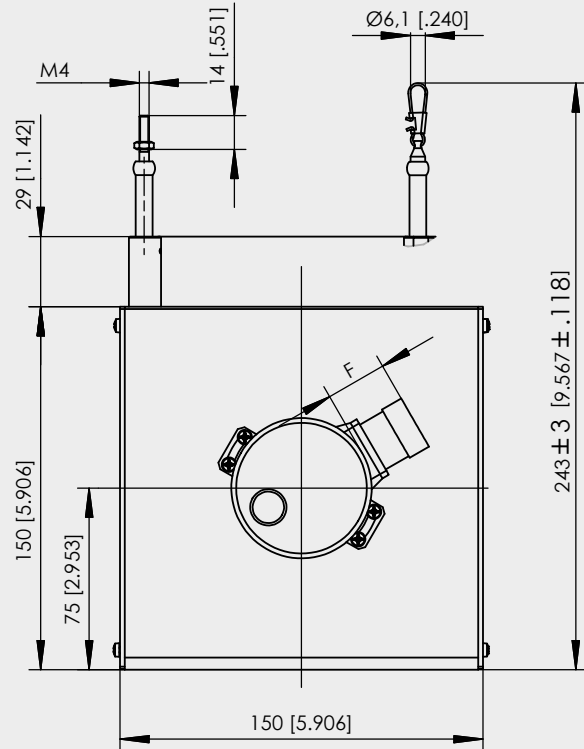


POSIWIRE®
WS19KT
Absolute or Incremental Encoder Output



Outline drawing
 WS19KT-5000

Option SB0



Dimensions E, F and L depend on the encoder type.

Dimensions in mm [inch]

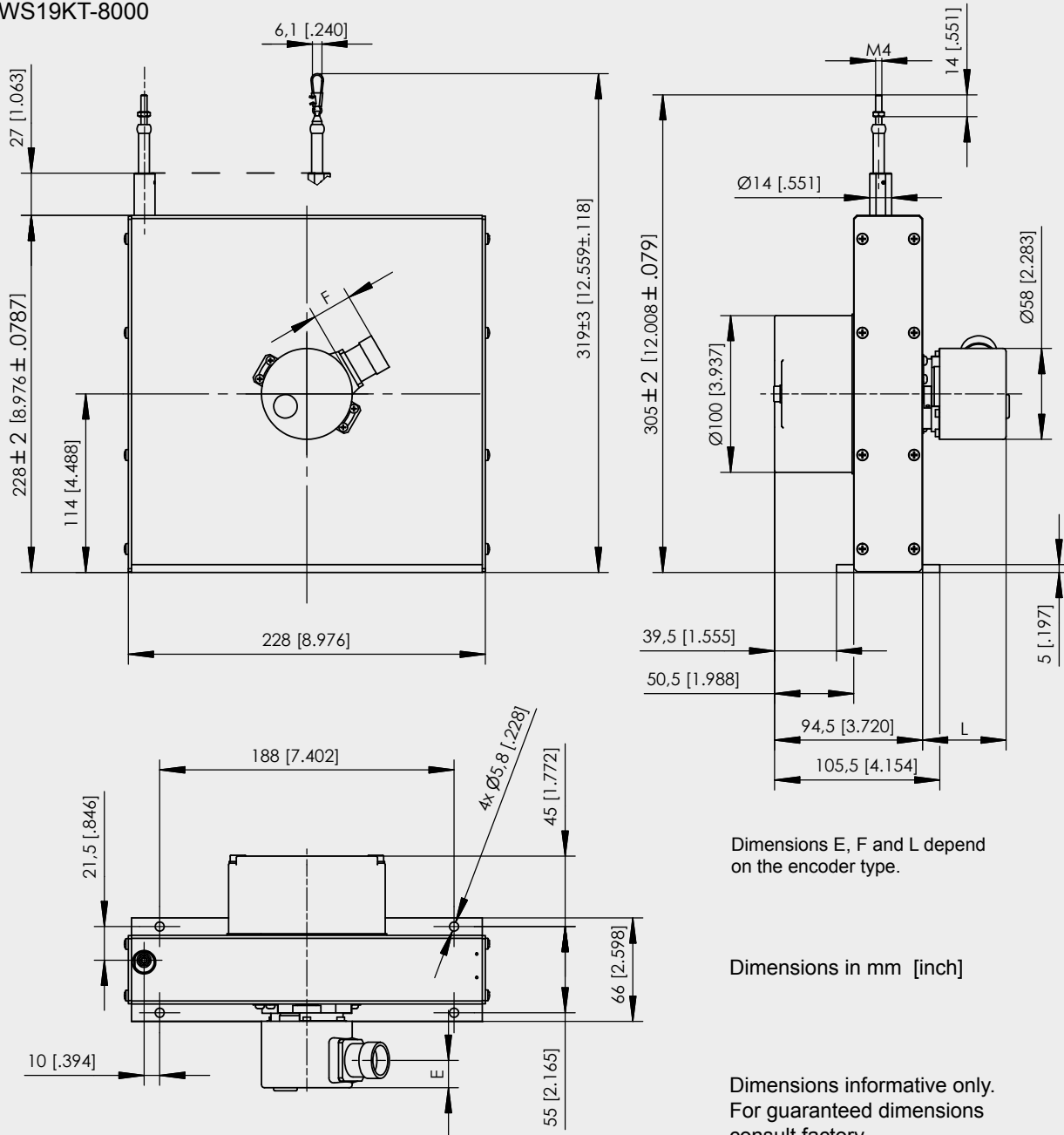
Dimensions informative only.
 For guaranteed dimensions consult factory.

POSIWIRE®
WS19KT
Absolute or Incremental Encoder Output



Outline drawing
 WS19KT-8000

Option SB0



Dimensions E, F and L depend on the encoder type.

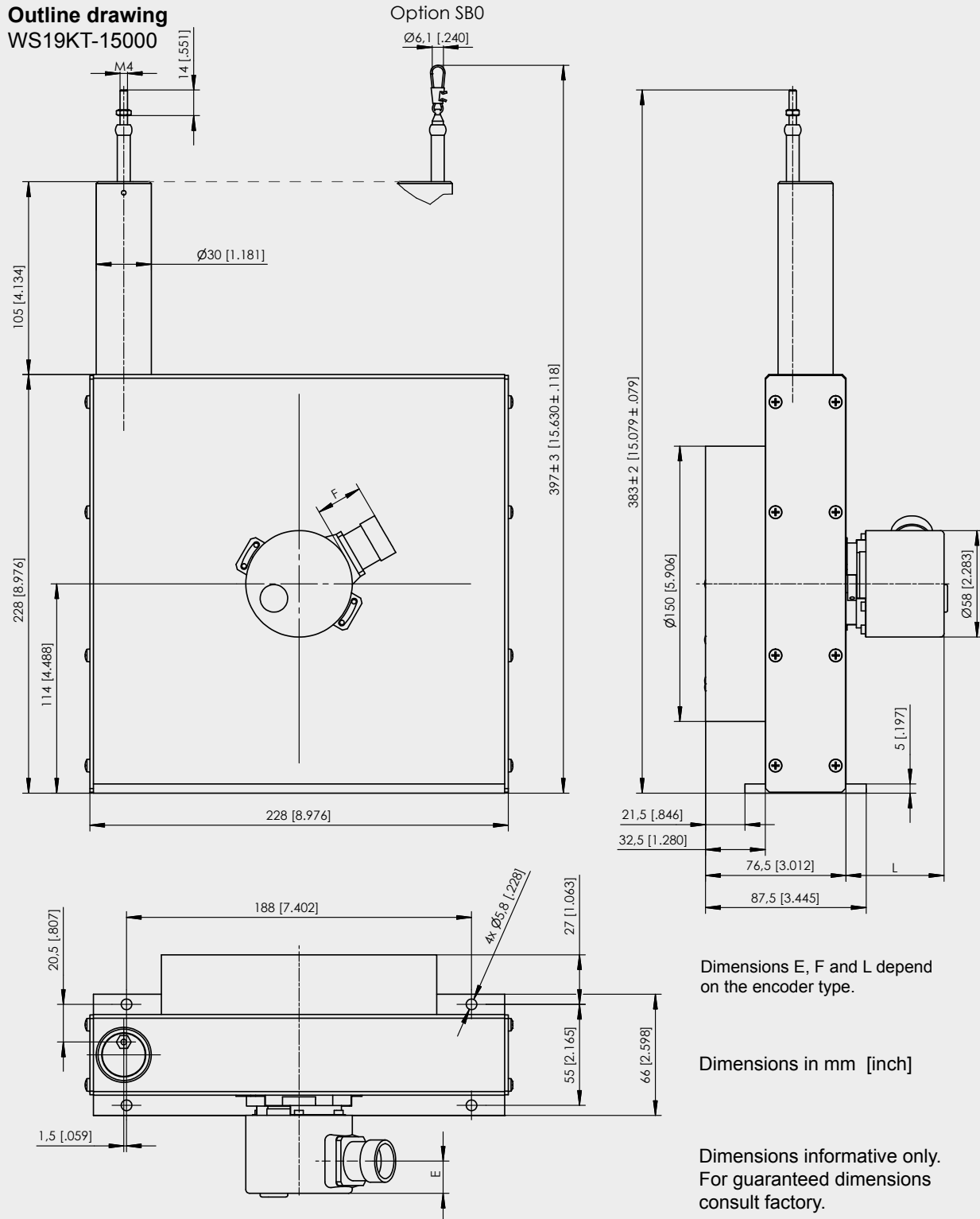
Dimensions in mm [inch]

Dimensions informative only.
 For guaranteed dimensions consult factory.

POSIWIRE®
WS19KT
Absolute or Incremental Encoder Output




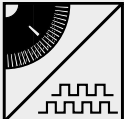
Outline drawing
WS19KT-15000



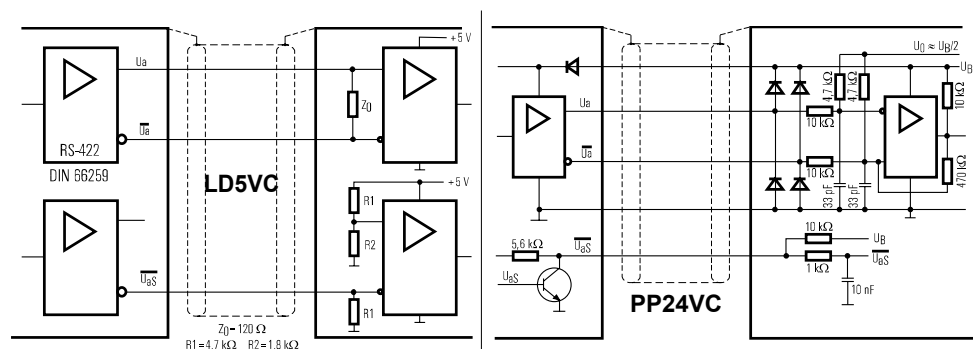
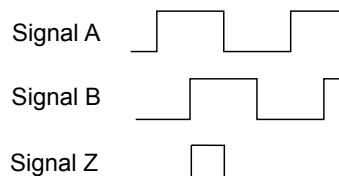
POSIWIRE® LD5VC and PP24VC Incremental Output



Signal conditioner LD5VC Incremental 	Interface	Line driver RS422
	Excitation voltage	5 V DC $\pm 10\%$
	Excitation current	150 mA max. w/o load
	Output frequency	300 kHz max.
	Output current	20 mA per channel
	Signal level	
	Ud High at Id=20 mA	≥ 2.5 V
	Ud Low at Id=20 mA	≤ 0.5 V
	Transition time positive edge	<100 ns
	Transition time negative edge	<100 ns
	Stability (temperature)	$\pm 20 \times 10^{-6}$ / °C f.s. (sensor mechanism)
	Operation temperature	-20 ... +85 °C
	Protection	Short circuit, overvoltage
EMC	According to EN 61326:2006	

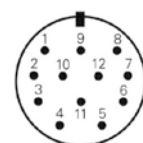
Signal conditioner PP24VC Incremental 	Interface	Push-pull line driver (24 V-HTL)
	Excitation voltage	10 ... 30 V DC
	Excitation current	150 mA max. w/o load
	Output frequency	300 kHz max.
	Output current	100 mA per channel
	Signal level	
	Ud High at Id=20 mA, Ub=24 V	≥ 21 V
	Ud Low at Id=20 mA, Ub=24 V	≤ 2.8 V
	Transition time positive edge	<200 ns
	Transition time negative edge	<200 ns
	Stability (temperature)	$\pm 20 \times 10^{-6}$ / °C f.s. (sensor mechanism)
	Operating temperature	-20 ... +85 °C
	Protection	Reverse polarity, short circuit, overvoltage
EMC	According to EN 61326:2006	

Output signals



Signal name	CONN-CONIN-12F, connector pin no.
Excitation +	12
Excitation GND (0 V)	10
Signal A	5
Signal \bar{A}	6
Signal B (A + 90°)	8
Signal B	1
Signal Z (reference pulse)	3
Signal \bar{Z}	4
Fault detection signal \bar{U}_{as}	7
Shield	Housing

View to sensor connector




CONN-CONIN-12F

POSIWIRE®

HSSI

Absolute SSI Encoder



Signal conditioner HSSI Absolute encoder synchronous serial 	Excitation voltage	10 ... 30 V DC
	Excitation current	100 mA
	Interface	Standard SSI
	Lines / drivers	Clock and data / RS422
	Code	Gray
	Resolution	12 + 12 Bit
	3 dB cutoff frequency	500 kHz
	Control input	$\overline{\text{Direction}}$
	Preset key	Zero adjustment with optical response
	Alarm output	Alarm bit (SSI option), warning bit
	Status LED	Green = OK, red = alarm
	Connection	12 pin male socket

Data format	Resolution	Clock												
		T1	T2	T3	...	T12	T13	...	T21	T22	T23	T24	T25	T26
		Data bits												
24 bit	M11	M10	M9	...	M0	S11	...	S3	S2	S1	S0	0		

Mx = multiturn bits, Sx = singleturn bits

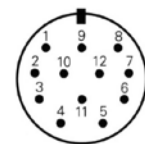
Transmission rate	Cable length	Baud rate	Note: Extension of the cable length will reduce the maximum transmission rate.
	< 50 m	< 400 kHz	
	< 100 m	< 300 kHz	
	< 200 m	< 200 kHz	
	< 400 m	< 100 kHz	

Signal wiring	Signal name	Color	Connector pin no.
	Excitation +	White	8
	Excitation GND (0 V)	Brown	1
	CLOCK	Yellow	3
	$\overline{\text{CLOCK}}$	Green	11
	DATA	Pink	2
	$\overline{\text{DATA}}$	Gray	10
	$\overline{\text{Direction}}$ *	Blue	5
	0 V Signal output	Black	12

* Excitation + = cw increasing code, 0 V = cw decreasing code

Connection

View to sensor
connector



CONN-CONIN-12F

POSIWIRE®
HPROF
Absolute Profibus Encoder



Interface HPROF
 Absolute encoder
 Profibus



Excitation voltage	10 ... 30 V DC
Excitation current	250 mA
Interface	RS485
Protocol	Profibus DP with encoder profile C2
Resolution	12 (10 ... 14) + 12 bit
Output code	Binary
Baud rate	Automatically selected between 9,6 kBaud and 12 MBaud
Programmability	Resolution, preset, direction
Integrated special functions	Velocity, acceleration, operating time
Bus terminating resistor	Selectable via DIP switch
Connection	Bus cover with T manifold
EMC	EN 61326: class A

Signal wiring

Signal name	Cable terminal no. (bus cover)
U _B in	1
0V in	2
U _B out	3
0V out	4
B in	5
A in	6
B out	7
A out	8

POSIWIRE®
HINT
Absolute Interbus Encoder




Interface HINT Absolute encoder Interbus 	Excitation voltage	10 ... 30 V DC
	Excitation current	250 mA
	Interface	Interbus, ENCOM profile K3 (configurable), K2
	Output code	32 Bit binary
	Baud rate	500 kBaud
	Data refresh	Every 600 µs
	Resolution	12 (10 ... 14) + 12 bit
	Programmability	Direction, preset, offset, resolution
	Connection	Bus cover with T manifold
	EMC	EN 50081-2, EN 50082-2

Data format Interbus K2/K3		Differential signals (RS485) ENCOM profile K3, K2, 32 Bit, binary process data				
	DT-Format	Supi address	0	1	2	3
	(according to the Phoenix company)	Byte No.	3	2	1	0
	ID code K2	36 H (= 54 dec.)				
	ID code K3	37 H (= 55 dec.)				

Signal wiring	Signal name	Cable terminal no. (bus cover)
		U _B +
	GND	2
	DI1	3
	$\overline{DI1}$	4
	DO1	5
	$\overline{DO1}$	6
	DO2	7
	$\overline{DO2}$	8
	DI2	9
	$\overline{DI2}$	10
	RBST	11
	GND	12

POSIWIRE®
HDEV
Absolute DeviceNet Encoder



Interface HDEV Absolute encoder DeviceNet 	Excitation voltage	10 ... 30 V DC
	Excitation current	250 mA
	Interface	CAN highspeed according to ISO/DIS 11898 CAN specification 2.0 A (11 bit identifier)
	Protocol	DeviceNet according rev. 2.0, programmable encoder
	Resolution	12 (10 ... 14) + 12 bit
	Output code	Binary
	MAC-ID	Selectable via DIP switch
	Data refresh	Every 5 ms
	Baud rate	Selectable via DIP switch: 125 kBaud, 250 kBaud, 500 kBaud
	Programmability	Resolution, preset, direction
	Bus terminating resistor	Selectable via DIP switch
	Connection	Bus cover with T manifold
	EMC	EN 50081-2, EN 50082-2

Recommended transmission	Characteristic impedance	135 ... 165 Ω (3 ... 20 MHz)
	Operating capacity	< 30 pF
	Loop resistance	< 110 Ω/km
	Wire diameter	> 0.63 mm
	Wire width	> 0.34 mm ²

Transmission rate	Segment length	Kbit/s
	500 m	125
	250 m	250
	100 m	500

Signal wiring	Signal name	Cable terminal no. (bus cover)
	U _b in	1
	0V in	2
	CAN-L	3
	CAN-H	4
	Drain	5
	Drain	6
	CAN-H	7
	CAN-L	8

POSIWIRE®
HCAN/HCANOP
Absolute CAN / CANopen Encoder



Interface
HCAN/HCANOP
 Absolute encoder
 CANopen/CAN Layer 2



Excitation voltage	10 ... 30 V DC
Excitation current	250 mA
Interface	CAN highspeed according to ISO/DIS 11898
Protocol	CANopen according DS301 with encoder profile DSP406, programmable encoder according class C2
Resolution	12 (10 ... 14) + 12 bit
Output code	Binary
Data refresh	Every millisecond (selectable), on request
Baud rate	Selectable 10 up to 1000 kbit/s
Base identifier	Selectable via DIP switch
Programmability	CANopen: direction, resolution, preset, offset CAN L2: direction, limit values
Integrated special functions	CANopen: velocity, acceleration, rotary axis, limit values CAN L2: direction, limit values
Connection	Bus cover with T manifold
EMC	EN 50081-2, EN 50082-2

Signal wiring

Signal name	Cable terminal no. (bus cover)
U _B in	1
0V in	2
CAN in – (dominant L)	3
CAN in + (dominant H)	4
CAN GND in	5
CAN GND out	6
CAN out + (dominant H)	7
CAN out – (dominant L)	8
0V out	9
U _B out	10